LEARNING WITH CONSTRAINTS Developmental issues

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Outline $\phi(f(x)) = 0$



What about a joint discovery of ϕ and f ?

$$\phi \circ f = 0$$

Unilateral and bilateral constraints

 $\psi_i(f(x)) \ge 0$ $\phi_i(x) = (-\psi(x))_+ := [\psi(x) > 0]\psi(x)$

Let's play with bilateral constraints ...

Quite tricky ...

$$y = f(x) = Ax$$

 $\bar{\phi} = By$
 $\bar{\phi}(f(x)) = BAx$
If $\bar{\phi}(f(x)) = BAx = 0$

the same holds for $BPP^{-1}A$

 $(A,B) \sim (P^{-1}A, PB)$

$$z = \frac{BPP^{-1}Ax}{\phi \circ f} \quad z = BAx$$
$$y = P^{-1}Ax \quad y = Ax$$

Formulation of Learning

 $f: \mathcal{X} \subset \mathbf{R}^d \to \mathcal{Y} \subset \mathbf{R}^n \text{ and } \phi: \mathcal{Y} \subset \mathbf{R}^n \to \mathcal{Z} \subset \mathbf{R}^m$ $\mathcal{A} \subset \mathcal{H}^2$ and $\mathcal{B} \subset \mathcal{H}^2$ knowledge map $f(\mathcal{X}) \subset \mathcal{Y}$ perceptual space concept space quantization over all the perceptual space m $\forall x \in \mathcal{X} : \bar{\phi}(f(x)) = \prod \phi_i(f(x)) = 0$ i=1 $\forall x \in \mathcal{X}_i: \phi_i(f(x)) = 0, \quad i = 1, \dots, \bar{m}$ $1 \leq \overline{m} \leq m$ $\mathcal{Q}_x = \{\mathcal{X}_i, i = 1, \dots, \overline{m} \leq m\}$

Covering of the perceptual space

 $\forall \mathbf{f} \in \mathcal{F}_i: \phi_i(\mathbf{f}) = 0, \quad i = 1, \dots, \bar{m}$

Example $\mathcal{X} = \{ (x, x_2) \in \mathbf{R}^2 : ((-2 < x_1 < 2) \land (x_2 = 0) \lor ((x_1 = 0) \land (x_2 > 0)) \}$ $f_2(x_1, x_2) = \left[-2 < x_1 < -\frac{1}{2} \right]$ $f_3(x_1, x_2) = \left\lceil \frac{1}{2} < x_1 < 2 \right\rceil$ $f_4(x_1, x_2) = \left[\left(-\frac{1}{2} < x_1 < \frac{1}{2} \right) \bigvee \left(x_2 > 0 \right) \right]$

$$\mathcal{X}_{1} = \left\{ (x_{1}, x_{2}) : \left(-1 < x_{1} < -\frac{1}{2} \right) \land \left(x_{2} = 0 \right) \right\} \qquad \mathcal{X} = \mathcal{X}_{1} \cup \mathcal{X}_{2} \cup \mathcal{X}_{3}$$
$$\mathcal{X}_{2} = \left\{ (x_{1}, x_{2}) : \left(\frac{1}{2} < x_{1} < 1 \right) \land \left(x_{2} = 0 \right) \right\} \qquad \mathcal{C}_{\mathcal{X}} = \mathbb{I}_{\mathcal{X}} \text{ cover}$$
$$\mathcal{X}_{3} = \left\{ (x_{1}, x_{2}) : \left(x_{1} = 0 \right) \land \left(x_{2} > 0 \right) \right\}$$

 $\forall x \in \mathcal{X}_1 : \phi_1 = f_1(x) f_2(x) - 1 = 0$ $\forall x \in \mathcal{X}_2 : \phi_2 = f_2(x) f_3(x) - 1 = 0$ $\forall x \in \mathcal{X}_3 : \phi_3 = f_4(x) - 1 = 0$

 $\mathcal{X}_4 = \{(x_1, x_2) : (-2 < x_1 < 2) \land (x_2 = 0)\} \dots$ supercover

So far ... learning from constraints

$$f_{\mathcal{X}}^{\star} = \underset{f \in \mathcal{C}_{\mathcal{X}}(\bar{\phi})}{\arg\min} \|f\|$$

given ...

we need parsimony ...

small $\|f\|$



probabilistic normalization

$$\sum_{i=1}^{m} \int_{\mathcal{X}} dx p_X(x) P_{R=i|X=x}(\phi \circ f) = \int_{\mathcal{X}} dx \left(\sum_{i=1}^{m} \frac{e^{-\phi_i(f(x))}}{\sum_{j=1}^{m} e^{-\phi_j(f(x))}}\right) p_X(x) = 1$$

$$P_{R=i}(\phi \circ f) = \int_{\mathcal{X}} dx p_X(x) \ p_{R=i|X=x}(\phi \circ f)$$
$$\simeq \frac{1}{|\mathcal{D}|} \sum_{x_{\kappa} \in \mathcal{D}} p_{R=i|X=x_{\kappa}}(\phi \circ f) := \langle P_{R=i}(\phi \circ f) \rangle_{\mathcal{D}}$$

Mutual Information $I_{X|R}$

$$\begin{split} H_{R|X}(\phi \circ f) &= E_{XR}[-\log P_{R|X}] \\ &- \int_{\mathcal{X}} dx p_X(x) \sum_{i=1}^m P_{R=i|X=x}(\phi \circ f) \log P_{R=i|X=x}(\phi \circ f) \\ &\simeq - \sum_{x_{\kappa} \in \mathcal{D}} \sum_{i=1}^m P_{R=i|X=x_{\kappa}}(\phi \circ f) \log P_{R=i|X=x_{\kappa}}(\phi \circ f). \end{split}$$

$$H_R(\phi \circ f) = -\sum_{i=1}^m P_{R=i}(\phi \circ f) \log P_{R=i}(\phi \circ f)$$

 $I_{X,R}(\phi \circ f) = H_R(\phi \circ f) - H_{R|X}(\phi \circ f)$ $I_{X,R}(\phi \circ f) \le H_R(\phi \circ f) \le \log m$

MMI

$$(f^{\star}, \phi^{\star}) = \underset{(f,\phi)\in\mathcal{A}\times\mathcal{B}}{\operatorname{arg\,max}} I_{X,R}(\phi \circ f)$$

$$f^{\star}(\bar{\phi}^{\star}) = \underset{(f,\phi)\in\mathcal{C}_{\mathcal{X}}(f,\bar{\phi}^{\star})}{\arg\min} \alpha \|f\| \qquad \text{parsimony}$$
$$\bar{\phi}^{\star}(f^{\star}) = \underset{(f,\phi)\in\mathcal{C}_{\mathcal{X}}(f^{\star},\phi)}{\arg\min} \left(\beta \|\bar{\phi}^{\star}\| - I_{X,R}(\bar{\phi}^{\star} \circ f)\right)$$

information-based index

MMI Stage-based learning

$$\phi_{0}, \left[f_{0}^{\star}(\bar{\phi}_{0}), \phi_{1}^{\star}(f_{0}^{\star})\right], \\ \left[f_{1}^{\star}(\bar{\phi}_{1}^{\star}), \phi_{2}^{\star}(f_{1}^{\star})\right], \\ \left[f_{2}^{\star}(\bar{\phi}_{2}^{\star}), \phi_{3}^{\star}(f_{2}^{\star})\right],$$

. . .

$$\begin{bmatrix} f_{\kappa-1}^{\star}(\bar{\phi}_{\kappa-1}^{\star}), \phi_{\kappa}^{\star}(f_{\kappa-1}^{\star}) \end{bmatrix}, \\ \begin{bmatrix} f_{\kappa}^{\star}(\bar{\phi}_{\kappa}^{\star}), \phi_{\kappa+1}^{\star}(f_{\kappa}^{\star}) \end{bmatrix}. \end{bmatrix}$$

$$f^{\star} = \lim_{\kappa \to \infty} f^{\star}_{\kappa}(\bar{\phi}^{\star}_{\kappa})$$
$$\phi^{\star} = \lim_{\kappa \to \infty} \phi^{\star}_{\kappa}(f^{\star}_{\kappa-1})$$

Developmental function

$$D(f,\phi) = ||(f,\phi)|| - I_{X,R}(\phi \circ f)$$

$$\begin{pmatrix} f^{\star} \\ \phi^{\star} \end{pmatrix} = \operatorname*{arg\,min}_{(f,\phi)\in\mathcal{C}_{\mathcal{X}}} D(f,\phi)$$

$$\bar{\phi}(f(x)) = \bar{\phi}_s(f(x)) \cdot \bar{\phi}_l(f(x))$$

given constraints learned constraints

Lagrangian approach by using neural nets